

# Dailin Hu

Data Scientist

hudailin@gmail.com | 949-664-3144

## PUBLICATIONS

StaTeS-SQL: Soft Q Learning with State-Dependent Temperature Scheduling. Master thesis, 2022.  
Hu D, Abbeel P, Fox R.

Reducing Variance in Temporal-Difference Value Estimation via Ensemble of Deep Networks. International Conference on Machine Learning, 2022.  
Liang L, Xu Y, McAleer S, Hu D, Ihler A, Abbeel P, Fox R.

Count-Based Temperature Scheduling for Maximum Entropy Reinforcement Learning. NeurIPS workshop on Deep Reinforcement Learning, 2021.  
Hu D, Abbeel P, Fox R.

Target Entropy Annealing for Discrete Soft Actor-Critic. NeurIPS workshop on Deep Reinforcement Learning, 2021.  
Xu Y, Hu D, Liang L, McAleer S, Abbeel P, Fox R.

Temporal-Difference Value Estimation via Uncertainty-Guided Soft Updates. NeurIPS workshop on Deep Reinforcement Learning, 2021.  
Liang L, Xu Y, McAleer S, Hu D, Ihler A, Abbeel P, Fox R.

## SKILLS

Programming languages

C\C++ • Python • C#

Tools & Utilities

PyTorch • JAX

• Git • Unity • Arduino • Raspberry Pi

## EDUCATION

UNIVERSITY OF CALIFORNIA, IRVINE  
Computer Science, M.S. | 2020-2022

UNIVERSITY OF CALIFORNIA, IRVINE  
Electrical Engineering and Computer Science Exchange Student |  
2019-2020

SOUTHEAST UNIVERSITY

Computer Science, B.S. | 2016-2020

## EXPERIENCE

### MICROSOFT GAMING, BLIZZARD

DATA SCIENTIST

2022 - Present | Irvine, CA

- Led development for a game-agnostic reinforcement-learning (RL) internal pipeline with JAX.
- Supported and maintained Hearthstone AI training pipeline.
- Worked across multiple franchises to create smart bot behavior. Led research and development for RL-based shooter bot navigation. Worked on smart multi-agent collaboration and adversarial behavior for in-game bots, supported by RL and LLM.

### MOTIONAL DRIVERLESS TECHNOLOGY

MOTION PLANNING RESEARCH SCIENTIST (INTERN)

2022 | Boston, MA

- Compared the self-driving behavior demonstrated by different state-of-the-art RL methods.
- Contributed to nu-Plan, the world's first closed-loop, ML-based planning benchmark for autonomous driving

### HPI RESEARCH CENTER IN MACHINE LEARNING AND DATA SCIENCE

RESEARCH FELLOW

2021-2022 | University of California, Irvine

- Built reinforcement learning and imitation learning based autonomous driving framework with the Duckietown self-driving project.
- Presented several methods for reducing the bias in training in Maximum Entropy Reinforcement learning. Demonstrating state-of-the-art performance on Atari 2600 benchmarks.

### INTELLIGENT DYNAMICS LAB

RESEARCH ASSISTANT

2019-2020 | University of California, Irvine

- Proposed a method such that it combines the advantage of both RL and Imitation Learning (IL), outperforming both RL and IL with limited data.
- Awarded UROP fellowship.

### SOUTHEAST UNIVERSITY

UNDERGRAD RESEARCH ASSISTANT

2018-2019 | China

- Built an online AI gaming platform for internal testing. Used Vue.js for front-end development and Django for backend development.
- Applied AlphaGo Zero's method to the game of connect-5, implemented with C++ & Python. Core algorithms include Monte Carlo Tree Search, Alpha-Beta Pruning and Convolutional Neural Networks. Awarded 3rd prize in the Chinese University Computer Games Championship National Final.
- Researched possibilities of combining Hierarchical RL with multi-agent RL methods.